

NAG Toolbox for MATLAB

g02dg

1 Purpose

g02dg calculates the estimates of the parameters of a general linear regression model for a new dependent variable after a call to g02da.

2 Syntax

```
[rss, cov, q, b, se, res, ifail] = g02dg(weight, wt, rss, ip, irank,
cov, q, svd, p, y, wk, 'n', n)
```

3 Description

g02dg uses the results given by g02da to fit the same set of independent variables to a new dependent variable.

g02da computes a *QR* decomposition of the matrix of p independent variables and also, if the model is not of full rank, a singular value decomposition (**svd**). These results can be used to compute estimates of the parameters for a general linear model with a new dependent variable. The *QR* decomposition leads to the formation of an upper triangular p by p matrix R and an n by n orthogonal matrix Q . In addition the vector $c = Q^T y$ (or $Q^T W^{1/2} y$) is computed. For a new dependent variable, y_{new} , g02dg computes a new value of $c = Q^T y_{\text{new}}$ or $Q^T W^{1/2} y_{\text{new}}$.

If R is of full rank, then the least-squares parameter estimates, $\hat{\beta}$, are the solution to

$$R\hat{\beta} = c_1,$$

where c_1 is the first p elements of c .

If R is not of full rank, then g02da will have computed an **svd** of R ,

$$R = Q_* \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix} P^T,$$

where D is a k by k diagonal matrix with nonzero diagonal elements, k being the rank of R , and Q_* and P are p by p orthogonal matrices. This gives the solution

$$\hat{\beta} = P_1 D^{-1} Q_{*1}^T c_1,$$

P_1 being the first k columns of P , i.e., $P = (P_1 P_0)$, and Q_{*1} being the first k columns of Q_* . Details of the **svd** are made available by g02da in the form of the matrix P^* :

$$P^* = \begin{pmatrix} D^{-1} P_1^T \\ P_0^T \end{pmatrix}.$$

The matrix Q_* is made available through the workspace of g02da.

In addition to parameter estimates, the new residuals are computed and the variance-covariance matrix of the parameter estimates are found by scaling the variance-covariance matrix for the original regression.

4 References

Golub G H and Van Loan C F 1996 *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Hammarling S 1985 The singular value decomposition in multivariate statistics *SIGNUM Newsl.* **20** (3) 2–25

Searle S R 1971 *Linear Models* Wiley

5 Parameters

5.1 Compulsory Input Parameters

1: **weight** – string

Indicates if weights are to be used.

weight = 'U' (Unweighted)

Least-squares estimation is used.

weight = 'W' (Weighted)

Weighted least-squares is used and weights must be supplied in array **wt**.

Constraint: **weight** = 'U' or 'W'.

2: **wt(*)** – double array

Note: the dimension of the array **wt** must be at least **n** if **weight** = 'W', and at least 1 otherwise.

If **weight** = 'W', **wt** must contain the weights to be used in the weighted regression.

If **wt**(*i*) = 0.0, the *i*th observation is not included in the model, in which case the effective number of observations is the number of observations with nonzero weights.

If **weight** = 'U', **wt** is not referenced and the effective number of observations is *n*.

Constraint: **wt**(*i*) ≥ 0.0 if **weight** = 'W', for *i* = 1, 2, ..., *n*.

3: **rss** – double scalar

The residual sum of squares for the original dependent variable.

Constraint: **rss** > 0.0.

4: **ip** – int32 scalar

p, the number of independent variables (including the mean if fitted).

Constraint: $1 \leq \mathbf{ip} \leq \mathbf{n}$.

5: **irank** – int32 scalar

The rank of the independent variables, as given by g02da.

Constraint: **irank** > 0, and if **svd** = **false**, then **irank** = **ip**, else **irank** ≤ **ip**.

6: **cov(ip × (ip + 1)/2)** – double array

The covariance matrix of the parameter estimates as given by g02da.

7: **q(ldq, ip + 1)** – double array

ldq, the first dimension of the array, must be at least **n**.

The results of the *QR* decomposition as returned by g02da.

8: **svd** – logical scalar

Indicates if a singular value decomposition was used by g02da.

svd = true

A singular value decomposition was used by g02da.

svd = false

A singular value decomposition was not used by g02da.

9: **p(*) – double array**

Note: the dimension of the array **p** must be at least **ip** if **svd = false**, and at least $\mathbf{ip} \times \mathbf{ip} + 2 \times \mathbf{ip}$ otherwise.

Details of the *QR* decomposition and **svd**, if used, as returned in array **p** by g02da.

If **svd = false**, only the first **ip** elements of **p** are used; these contain the zeta values for the *QR* decomposition (see f08ae for details).

If **svd = true**, the first **ip** elements of **p** contain the zeta values for the *QR* decomposition (see f08ae for details) and the next $\mathbf{ip} \times \mathbf{ip} + \mathbf{ip}$ elements of **p** contain details of the singular value decomposition.

10: **y(n) – double array**

The new dependent variable, y_{new} .

11: **wk(5 × (ip – 1) + ip × ip) – double array**

If **svd = true**, **wk** must be unaltered from the previous call to g02da or g02dg.

If **svd = false**, **wk** is used as workspace.

5.2 Optional Input Parameters

1: **n – int32 scalar**

Default: The dimension of the arrays **y**, **res**. (An error is raised if these dimensions are not equal.)
 n , the number of observations.

Constraint: $n \geq \mathbf{ip}$.

5.3 Input Parameters Omitted from the MATLAB Interface

ldq

5.4 Output Parameters

1: **rss – double scalar**

The residual sum of squares for the new dependent variable.

2: **cov(ip × (ip + 1)/2) – double array**

The upper triangular part of the variance-covariance matrix of the **ip** parameter estimates given in **b**. They are stored packed by column, i.e., the covariance between the parameter estimate given in $\mathbf{b}(i)$ and the parameter estimate given in $\mathbf{b}(j)$, $j \geq i$, is stored in $\mathbf{cov}(j \times (j - 1)/2 + i)$.

3: **q(ldq, ip + 1) – double array**

The first column of **q** contains the new values of c , the remainder of **q** will be unchanged.

4: **b(ip) – double array**

The least-squares estimates of the parameters of the regression model, $\hat{\beta}$.

- 5: **se(ip)** – double array
The standard error of the estimates of the parameters.
- 6: **res(n)** – double array
The residuals for the new regression model.
- 7: **ifail** – int32 scalar
0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

ifail = 1

On entry, **ip** < 1,
or **n** < **ip**,
or **irank** ≤ 0,
or **svd** = false and **irank** ≠ **ip**,
or **svd** = true and **irank** > **ip**,
or **ldq** < **n**,
or **rss** ≤ 0.0,
or **weight** ≠ 'U' or 'W'.

ifail = 2

On entry, **weight** = 'W' and a value of **wt** < 0.0.

7 Accuracy

The same accuracy as g02da is obtained.

8 Further Comments

The values of the leverages, h_i , are unaltered by a change in the dependent variable so a call to g02fa can be made using the value of **h** from g02da.

9 Example

```
weight = 'U';
wt = [0];
rss = 22.222679999999987;
ip = int32(5);
irank = int32(4);
cov = [0.1481786666666657;
       0.03704466666666638;
       0.7038486666666622;
       0.03704466666666652;
       -0.2222679999999989;
       0.7038486666666626;
       0.03704466666666648;
       -0.2222679999999987;
       -0.2222679999999985;
       0.7038486666666621;
       0.03704466666666641;
       -0.2222679999999984;
       -0.2222679999999987;
       -0.2222679999999985;
```

```

0.70384866666666622];
q = [-132.3142479415325, -3.464101615137754, -0.866025403784439, -
0.8660254037844387, ...
-0.8660254037844387, -0.8660254037844387;
-4.3849999999999992, 0.2542949013547401, 1.5, -0.5000000000000001, -
0.5000000000000001, -0.5000000000000001;
3.450681092190354, 0.2542949013547401, 0.2464408878569322, -
1.414213562373095, ...
0.7071067811865476, 0.7071067811865477;
-4.564215887385989, 0.2542949013547401, 0.2464408878569322, -
0.1493782079840455, -1.224744871391589, 1.224744871391589;
-0.5165745490611717, 0.2542949013547401, 0.2464408878569322, -
0.1493782079840455, ...
-0.2512250416211346, 3.684598669906146e-16;
-1.786105166371516, 0.2542949013547401, 0.2464408878569322,
0.4236386677182777, ...
0.04757984926531376, 0.05853513115087475;
-2.040746763558067, 0.2542949013547401, 0.2464408878569322, -
0.1493782079840455, ...
-0.2512250416211346, 0.4717748148066523;
1.699599417218472, 0.2542949013547401, -0.3431208422711533, -
0.05795805473930137, ...
-0.09747415577321789, 0.2226984422646312;
1.338178326423549, 0.2542949013547401, 0.2464408878569322, -
0.1493782079840455, ...
0.4136728082784363, 0.1941369084874573;
2.919599417218471, 0.2542949013547401, -0.3431208422711533, -
0.05795805473930137, ...
-0.09747415577321789, 0.2226984422646312;
-1.151821673576453, 0.2542949013547401, 0.2464408878569322, -
0.1493782079840455, ...
0.4136728082784363, 0.1941369084874573;
0.2738948336284861, 0.2542949013547401, 0.2464408878569322,
0.4236386677182777, ...
0.04757984926531376, 0.05853513115087475];
svd = true;
p = [1.135198279858991;
1.13078348304906;
1.234006904805161;
1.228003039942231;
1.263332232672042;
3.872983346207417;
1.732050807568878;
1.732050807568878;
1.732050807568877;
1.64780261914309e-16;
0.2309401076758503;
8.35089227579159e-18;
-1.238223776129407e-17;
7.900875770685859e-17;
-0.447213595499958;
0.0577350269189626;
0.2871305767251709;
0.2022129403845741;
-0.3559016137228031;
0.447213595499958;
0.05773502691896256;
0.03726461792122844;
0.271286303307133;
0.4183480487454616;
0.447213595499958;
0.05773502691896257;
0.1515575558927682;
-0.4677758485215264;
0.0906424999201606;
0.447213595499958;
0.05773502691896258;
-0.4759527505391677;
-0.005723395170180857;
-0.153088934942819;

```

```

    0.4472135954999578];
y = [63;
     69;
     68;
     71;
     68;
     65;
     65;
     66;
     72;
     67;
     70;
     67];
wk = [-1;
     4.888782090057172e-17;
     3.783865581974411e-17;
     3.205148747669446e-17;
     2.127304033926049e-17;
     -7.232084855102773e-18;
     0.574261153450342;
     -0.282082169979652;
     -0.7685400295478783;
     -1.766548161010173e-16;
     1.072333245697965e-17;
     0.4044258807691484;
     -0.7184712955241166;
     0.5658963725559621;
     -3.152388336389935e-17;
     -6.842359129558908e-17;
     -0.7118032274456063;
     -0.635789781993599;
     -0.2985088248453474;
     7.896994727506343e-17;
     2.12730403392605e-17;
     1.57267977670022e-16;
     -8.430959034105682e-17;
     -1.677854456096144e-16;
     0.9999999999999999;
     0.2886751345948128;
     0.03726461792122845;
     0.271286303307133;
     0.4183480487454616;
     5;
     3.25;
     5.25;
     4.25;
     5.25;
     6.070050924028785e-16;
     0.7071067811865474;
     -0.5700260616371526;
     0.9995120760870788;
     1;
     0.7071067811865475;
     0.8216266117004956;
     0.03123475237772124;
     5.777618349603308e-32;
     -0.7071067811865476;
     -0.5700260616371526];
[rssOut, covOut, qOut, b, se, res, ifail] = ...
    g02dg(weight, wt, rss, ip, irank, cov, q, svd, p, y, wk)

rssOut =
    24.0000
covOut =
    0.1600
    0.0400
    0.7600
    0.0400
   -0.2400
    0.7600

```

```

0.0400
-0.2400
-0.2400
0.7600
0.0400
-0.2400
-0.2400
-0.2400
0.7600
qOut =
-234.1155  -3.4641  -0.8660  -0.8660  -0.8660  -0.8660
-4.5000    0.2543   1.5000  -0.5000  -0.5000  -0.5000
 3.5355    0.2543   0.2464  -1.4142   0.7071   0.7071
-4.4907    0.2543   0.2464  -0.1494  -1.2247   1.2247
-0.5880    0.2543   0.2464  -0.1494  -0.2512   0.0000
-2.1727    0.2543   0.2464   0.4236   0.0476   0.0585
-2.6415    0.2543   0.2464  -0.1494  -0.2512   0.4718
 1.6690    0.2543  -0.3431  -0.0580  -0.0975   0.2227
 0.9087    0.2543   0.2464  -0.1494   0.4137   0.1941
 2.6690    0.2543  -0.3431  -0.0580  -0.0975   0.2227
-1.0913    0.2543   0.2464  -0.1494   0.4137   0.1941
-0.1727    0.2543   0.2464   0.4236   0.0476   0.0585
b =
54.0667
11.2667
12.6000
16.9333
13.2667
se =
0.4000
0.8718
0.8718
0.8718
0.8718
res =
-2.3333
 1.6667
 1.3333
-0.0000
 0.6667
-1.6667
-2.3333
 0.6667
 1.0000
 1.6667
-1.0000
 0.3333
ifail =
0

```